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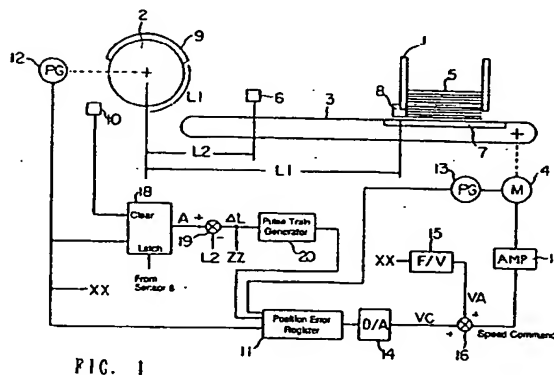
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54 SHEET FEEDING DEVICE.

⑤7 A sheet feeding device for feeding paper sheets mounted on a hopper by a suction conveyor provided on the lower part of the hopper to the printing machine one by one, which device is provided with a motor for driving the suction conveyor, a sensor for detecting the forward end of a sheet conveyed by the conveyor, and a control device for controlling the motor so as to drive the motor synchronously with the plate cylinder of the printing machine and for correcting phases of the plate cylinder and the sheet on receiving a sensor detected signal, whereby mechanical error in sucking a sheet is corrected and accuracy in sheet feeding is improved.



Technical Field

This invention relates to a sheet feeding apparatus to feed sheets of corrugated cardboard and the like piled up in a hopper to a printing press piece by piece.

Background Technologies

Conventional sheet feeding apparatus having, at bottom of a hopper, a kicker moving back and forth to push out the lowest bottom sheet in the hopper, or an apparatus having a suction conveyor and controlling only conveyor speed with motor.

A sheet feeding apparatus of the type having a kicker has such disadvantages that sheets are damaged at their surfaces contacting with the kicker in case of sheets of lower stiffness and that sheets are not always timely fed to printing press. A sheet feeding apparatus of the type having a suction conveyor and controlling only conveyor speed with motor has such a disadvantage that accuracy to feed sheet to printing press is poor due to untimely suction of sheets.

Disclosure of the Invention

It is an object of this invention to provide a sheet feeding apparatus enabling to eliminate the said disadvantages of conventional apparatuses and to feed sheets without vacancies of shoot feeding and without damage to sheets.

Another object of this invention is to provide a sheet feeding apparatus enabling to improve sheet feeding accuracy by correction of mechanical error at suction of sheets by conveyor

A further object of this invention is to provide a sheet feeding apparatus enabling to correct parallel error against a plate cylinder.

The sheet feeding apparatus of the first invention for feeding sheets piled up in a hopper, piece by piece, to a printing press from a suction conveyor installed at bottom of the hopper, comprising,

a motor for driving the suction conveyor,

a sensor positioned above the suction conveyor for detecting front edges of sheets being transferred, and

a control unit for equalizing speed of the motor with speed of a plate cylinder of printing press and for adjusting phase of the sheet to phase of a press plate on the plate cylinder with a detection signal of the sensor,

whereby sheet feeding accuracy is improved by correction of mechanical errors at suction of sheets.

The sheets feeding apparatus of the second invention for feeding sheets piled up in a hopper, piece by piece, to a printing press from first and

second suction conveyors installed in parallel at bottom of the hopper, comprising,

a first motor for driving the first suction conveyor,

a second motor for driving the second suction conveyor,

a first sensor positioned above the first suction conveyor for detecting front edges of sheets being transferred,

a second sensor positioned above the second suction conveyor for detecting front edges of sheets being transferred,

a first control unit for equalizing speed of the first motor with speed of a plate cylinder of printing press and for adjusting phase of the sheet to phase of a press plate on the plate cylinder with a detection signal of the first sensor, and

a second control unit for equalizing speed of the second motor with speed of the plate cylinder of printing press for adjusting phase of the sheet to phase of the press plate with the detection signal of the first sensor, and for correcting parallel error of the sheet against the press plate with detection signals of the first and second sensors,

whereby sheet feeding accuracy is improved by correction of mechanical error and parallel error at suction of sheets.

Brief Description of Drawings

Fig.1 shows the construction of an embodiment of the first invention.

Fig.2 is a plan view of the embodiment shown in Fig.1.

Fig.3 is a plan view of an embodiment of the second invention.

Fig.4 and Fig.5 show the construction of the embodiment shown in Fig.3.

Best Mode for Executing the Invention

Fig.1 and Fig.2 are a construction drawing and a plan view, respectively, of an embodiment where a sheet feeding apparatus of the first invention was applied to a flexographic printing press.

This sheet feeding apparatus includes a hopper 1 to pile up corrugated cardboard sheet 5, a suction conveyor 3 extended from bottom of the hopper to a plate cylinder 2 of a printing press, a servo motor 4 for driving the suction conveyor 3, and a sensor 6 provided to detect front edges of sheets for information of the suction conveyor 3.

A timing belt is used for the suction conveyor 3, and non-slippery material is adhered to surface of the belt. Because the suction conveyor is not a feature of this invention, usual suction conveyor can be used.

The servo motor 4 for driving the conveyor is

controlled by a control unit as shown in Fig.1, and this control unit comprises a servo amplifier 17 to control speed of the servo motor 4, a pulse tacho-generator (PG) 13 installed at the servo motor 3, a pulse tacho-generator (PG) 12 installed at the plate cylinder 2, an origin sensor 10 to detect origin of the plate cylinder 2, an absolute position counter 18 to detect absolute position of the plate cylinder 2, a subtracter 19, a pulse train generator 20, a position error register 11, a D/A converter 14, an F/V converter 15, and an adder 16.

As shown in Fig.1, the suction conveyor 3 has a common vacuum gate 7 connected to printer press line shaft (not shown in Fig.1), and a sheet 5 is taken out from the hopper 1 by up-and-down movement of this gate and is fed to the printing press by the conveyor 3.

The distance L1, in the parallel direction with the conveyor, between a stopper 8 of the hopper 1 and the lower reference point of plate cylinder 2 is set so as to become equal to a circumferential distance of the plate cylinder between front edge of a press plate 9 installed on the plate cylinder 2 and the lower reference point. The sensor 6 to detect front edges of sheets is positioned at a distance L2 from the lower reference point of plate cylinder 2 in the parallel direction with the conveyor.

In the sheet feeding apparatus having the above-mentioned construction, when the front edge of press plate 9 is located at a position in a distance L1 from the lower reference point of plate cylinder 2, a sheet 5 in the hopper 1 is sucked to the suction conveyor 3 by up-and-down movement of the vacuum gate 7, provided that clearance of stopper 8 is adjusted so as to feed sheets piece by piece. By the above functions, both of the front edge of sheet 5 and the front edge of press plate 9 are located at a position in a distance L1 from the lower reference point of plate cylinder, and thus, approximate phase adjustment is completed.

Then, the sheet 5 is fed to the printing press from the suction conveyor 3. Speed equalization of the servo motor 4 with the plate cylinder 2 and phase adjustment of the sheet 5 to the press plate 9 at feeding the sheet 5 to the printing press are explained below in detail.

At first, the speed equalization of the servo motor 4 with the plate cylinder 2 is described. To the position error register 11, pulses generated by the pulse tacho-generator 12 installed at the plate cylinder 2 are sent as adding input, and pulses generated by the pulse tacho-generator 13 installed at the servo motor 4 are sent as a subtracting input. Then, the deviation of the number of pulses sent from the pulse tacho-generator 13 from the number of pulses sent from the pulse tacho-generator 12 is calculated. This deviation is converted by the D/A converter 14, and then, is provided as

voltage output VC. This voltage output expresses the speed difference between the plate cylinder 2 and the servo motor 4, i.e. the speed difference between the plate cylinder 2 and the suction conveyor 3.

In the meantime, the F/V converter 15 converts the pulses from the pulse tacho-generator 12 to voltage signal VA. The voltage signals VC and VA are added together by the adder 16, producing speed command. This speed command is an input to the servo amplifier 17 and controls the speed of servo motor 4, and thus, the speed of suction conveyor 3.

By the above-mentioned procedures, the speed equalization of the servo motor 4 with the plate cylinder 2 is performed. By this way, the speed of suction conveyor 3 follows the speed of plate cylinder 2. But with this speed equalization only, mechanical error caused at suction of a sheet by the suction conveyor 3 remains as error in the phase of sheet 5 from the phase of press plate 9, and produces misalignment of printing. Therefore, it is necessary to correct this phase error.

The correction of the phase error is explained below.

When the sensor 6 detects front edge of a sheet 5 being transferred by the suction conveyor 3, the absolute position counter 18, which is cleared when the origin sensor 10 detects the origin of plate cylinder 2, is latched and outputs the value A. This value A expresses the absolute position of the front edge of press plate when the front edge of a sheet is detected. The subtracter 19 performs the calculation of $\Delta L = A - L2$. ΔL expresses the position difference between the front edge of sheet and the front edge of press plate, i.e. the position difference between the sheet 5 and the press plate 9. The error in the position of the sheet 5 from the position of the press plate 9 at feeding the sheet is corrected, having the pulse train generator 20 generate error correction pulses whose number is proportional to ΔL , and inputting the pulses to the position error register 11. For example, in case that the phase of press plate is ahead of the phase of sheet, the error correction pulses are sent to the position error register 11 in adding direction in order to advance the phase of sheet, and on the contrary, if the phase of press plate is behind the phase of sheet, the error correction pulses are sent to the position error register 11 in subtracting direction in order to delay the phase of sheet. By this way, during the period that the error correction pulses are generated, the speed command voltage sent to the servo amplifier 17 for driving the servo motor is increased or decreased, the speed of servo motor 4 varies in accordance with the speed command voltage, the equalization of the phase of sheet 5 with the phase of press

plate 9 is performed, and as mentioned above, the servo motor 4 is operated, being equalized with the circumferential speed of plate cylinder 2.

Because the sheet feeding apparatus of this embodiment corrects the mechanical error caused at suction of sheets by the suction conveyor as explained above, the sheet feeding accuracy can be improved.

A practice example of the second invention is explained below.

Fig.3 is a plan of a sheet feeding apparatus of this embodiment where the sheet feeding apparatus was applied to a flexographic printing press, same as the above-mentioned embodiment. This sheet feeding apparatus includes a hopper 1 to pile up corrugated cardboard sheets 5, two suction conveyors 3a and 3b extended in parallel from bottom of the hopper to a plate cylinder 2 of a printing press, two servo motors 4a and 4b for driving the suction conveyors 3a and 3b, and two sensors positioned above the suction conveyors 3a and 3b on straight lines perpendicular to the flow direction of sheets respectively.

Same as the above-mentioned embodiment, timing belts are used for the suction conveyors 3a and 3b, and non-slippery material is adhered to surfaces of the belts.

Each of the servo motors 4a and 4b for driving the conveyors is controlled by a separate control unit. Fig.4 shows the control unit for the servo motor 4a and Fig.5 shows the control unit for the servo motor 4b, together with a side view of the hopper 1, suction conveyors 3a and 3b, and plate cylinder 2. When the same components as those for the control unit shown in Fig.1 are used for the control units shown in Fig.4 and Fig.5, the same reference numbers as those shown in Fig.1 are used in Fig.4 and Fig.5. When the components corresponding to those for the control unit shown in Fig.1 are used for the control units shown in Fig.4 and Fig.5, the same reference numbers as those shown in Fig.1 are used with suffixes of "a" and "b" in Fig.4 and Fig.5.

Namely, the control units shown in Fig.4 and Fig.5 have pulse tacho-generators 13a and 13b corresponding to the pulse tacho-generator 13 shown in Fig.1, position error registers 11a and 11b corresponding to the position error register 11 in Fig.1, D/A converters 14a and 14b corresponding to the D/A converter 14 in Fig.1, F/V converters 15a and 15b corresponding to the F/V converter 15 in Fig.1, adders 16a and 16b corresponding to the adder 16 in Fig.1, servo amplifiers 17a and 17b corresponding to the servo amplifier 17 in Fig.1, an absolute position counter 18a corresponding to the absolute position counter 18 in Fig.1, a subtracter 19a corresponding to the subtracter 19 in Fig.1, and pulse train generators 20a and 20b corre-

sponding to the pulse train generator 20 in Fig.1. Fig. 5 differs from Fig.4 in the fact that the control unit shown in Fig.5 includes a logic circuit 21, a counter 22 and an adder 23. The logic circuit 21 and the counter 22 are performing correction of parallel of sheets.

In the sheet feeding apparatus shown in Fig.4 and Fig.5, the suction conveyors 3a and 3b have a common vacuum gate 7 connected to the printing press line shaft (not shown in the figures), and a sheet 5 is taken out from the hopper 1 by up-and-down movement of this gate and is fed to a printing press by the suction conveyors 3a and 3b.

The distance L1, in the parallel direction with the conveyors, between a stopper 8 of the hopper and the lower reference point of plate cylinder 2 is set so as to become equal to the circumferential distance between front edge of a press plate 9 installed on the plate cylinder 2 and the lower reference point of plate cylinder. The sensors 6a and 6b to detect front edges of sheets are positioned at a distance L2 from the lower reference point of plate cylinder 2 in parallel direction with the suction conveyors 3a and 3b.

In the sheet feeding apparatus having the construction explained above, when the front edge of press plate 9 is located at a position in a distance L1 from the lower reference point of plate cylinder, a sheet 5 in the hopper 1 is sucked to the suction conveyors 3a and 3b by up-and-down movement of the vacuum gate 7. By the above functions, both of the front edge of sheet 5 and the front edge of press plate 9 are located at a position in a distance L1 from the lower reference point of plate cylinder, and thus, approximate phase adjustment is completed. The sheet 5 is fed to the printing press from the suction conveyors 3a and 3b. Speed equalization of each of the servo motors 4a and 4b with the plate cylinder 2, adjustment of the phase of sheets 5 to the phase of press plate 9 and correction of parallel error of the sheet 5 are explained below.

At first, the speed equalization and the phase adjustment are described. The control unit shown in Fig.4 has the same construction as the control unit shown in Fig.1, performs the same functions as those of the control unit shown in Fig.1, and provides speed equalization of the servo motor 4a with the press plate 2 and adjustment of the phase of sheet 5 to the phase of press plate 9.

The position error ΔL , which is the output of the subtracter 19a of the control unit shown in Fig.4, is sent to the adder 23 of the control unit shown in Fig.5. Then, by the functions of the pulse train generator 20b, the position error register 11b, the D/A converter 14b, the F/V converter 15b and the adder 16b, speed equalization of the servo motor 4b with the plate cylinder 2 and adjustment

of the phase of sheet 5 to the phase of press plate 9 are performed.

Now, the correction of parallel error of sheet is explained. Assuming that the sheet 5 being transferred is not in parallel with the plate cylinder 2 but slants against the plate cylinder 2 due to mechanical error caused at suction of sheet by the suction conveyors, the sensors 6a and 6b to detect front edge of sheet do not generate detection signals simultaneously, but generate the signals with a time interval. These detection signals are sent to the logic circuit 21 of the control unit shown in Fig.5. The logic circuit 21 generates signal to clear or latch the counter 22 which counts the pulses sent from the pulse tacho-generator 13b. Therefore, by detecting advance or delay in phase of the front edge of sheet by the logic circuit 21 and by counting pulses during this advance or delay by the counter 22, parallel error B of the sheet against the plate cylinder is obtained and is added to the position error ΔL at the adder 23. Thus, correction of the parallel error is performed. Namely, parallel of sheet 5 with the plate cylinder 2 is adjusted by increasing or decreasing speed command voltage and thus, by increasing or decreasing speed of the suction conveyor 3b.

Because the sheet feeding apparatus of this embodiment can correct not only the position error of sheet but also the parallel error of sheet, using two suction conveyors installed in parallel, as explained above, further improvement of sheet feeding accuracy becomes possible.

Though the embodiment explained above has two suction conveyors, the number of suction conveyors is not limited to two. For example, in case five parallel suction conveyors are used, two each conveyors on the both sides are driven by a separate servo motor.

Industrial Applicability

A sheet feeding apparatus of this invention uses a suction conveyor, and speed equalization and position error correction are applied to servo motor for driving the suction conveyor. Therefore, a sheet feeding apparatus having high sheet feeding accuracy can be provided.

It is also possible to provide a sheet feeding apparatus having extremely high sheet feeding accuracy, by using at least two suction conveyors and by applying speed equalization, position error correction and parallel error correction to servo motors to drive the suction conveyors.

Claims

1. A sheet feeding apparatus for feeding sheets piled up in a hopper, piece by piece, to a

printer from a suction conveyor installed at bottom of the hopper, comprising;

a motor for driving the suction conveyor,

a sensor positioned above the suction conveyor for detecting front edges of sheets being transferred, and

a control unit for equalizing speed of the motor with speed of a plate cylinder of printing press and for adjusting phase of the sheet to phase of a press plate on the plate cylinder with a detection signal of the sensor,

whereby sheet feeding accuracy is improved by correction of mechanical error at suction of sheets.

2. A sheet feeding apparatus as set forth in claim 1 wherein the control unit having,

means for obtaining speed difference between the plate cylinder and the suction conveyor and for equalizing speed of the motor with speed of the plate cylinder based on the speed difference, and

means for obtaining position difference between the sheet and the press plate and for adjusting phase of the sheet to phase of the plate cylinder based on the position difference.

3. A sheet feeding apparatus for feeding sheets piled up in a hopper, piece by piece, to a printing press from first and second suction conveyors installed in parallel at bottom of the hopper, comprising;

a first motor for driving the first suction conveyor,

a second motor for driving the second suction conveyor,

a first sensor positioned above the first suction conveyor for detecting front edges of sheets being transferred,

a second sensor positioned above the second suction conveyor for detecting front edges of sheets being transferred,

a first control unit for equalizing speed of the first motor with speed of a plate cylinder of printing press and for adjusting phase of the sheet to phase of a press plate on the plate cylinder with a detection signal of the first

sensor, and

a second control unit for equalizing speed
of the second motor with speed of the plate
cylinder of printing press, for adjusting phase
of the sheet to phase of the press plate with
the detection signal of the first sensor, and for
correcting parallel error of the sheet against
the press plate with detection signals of the
first and second sensors,

whereby sheet feeding accuracy is improved
by correction of mechanical error and parallel
error at suction of sheets.

4. A sheet feeding apparatus as set forth in claim
3 wherein the first and second control units,
each having,

means for obtaining speed difference be-
tween the plate cylinder and the first and sec-
ond suction conveyors and for equalizing
speed of the first and second motors with
speed of the plate cylinder based on the
speed difference, and

means for obtaining position difference be-
tween the sheet and the press plate and for
adjusting phase of the sheet to phase of the
plate cylinder based on the position difference.

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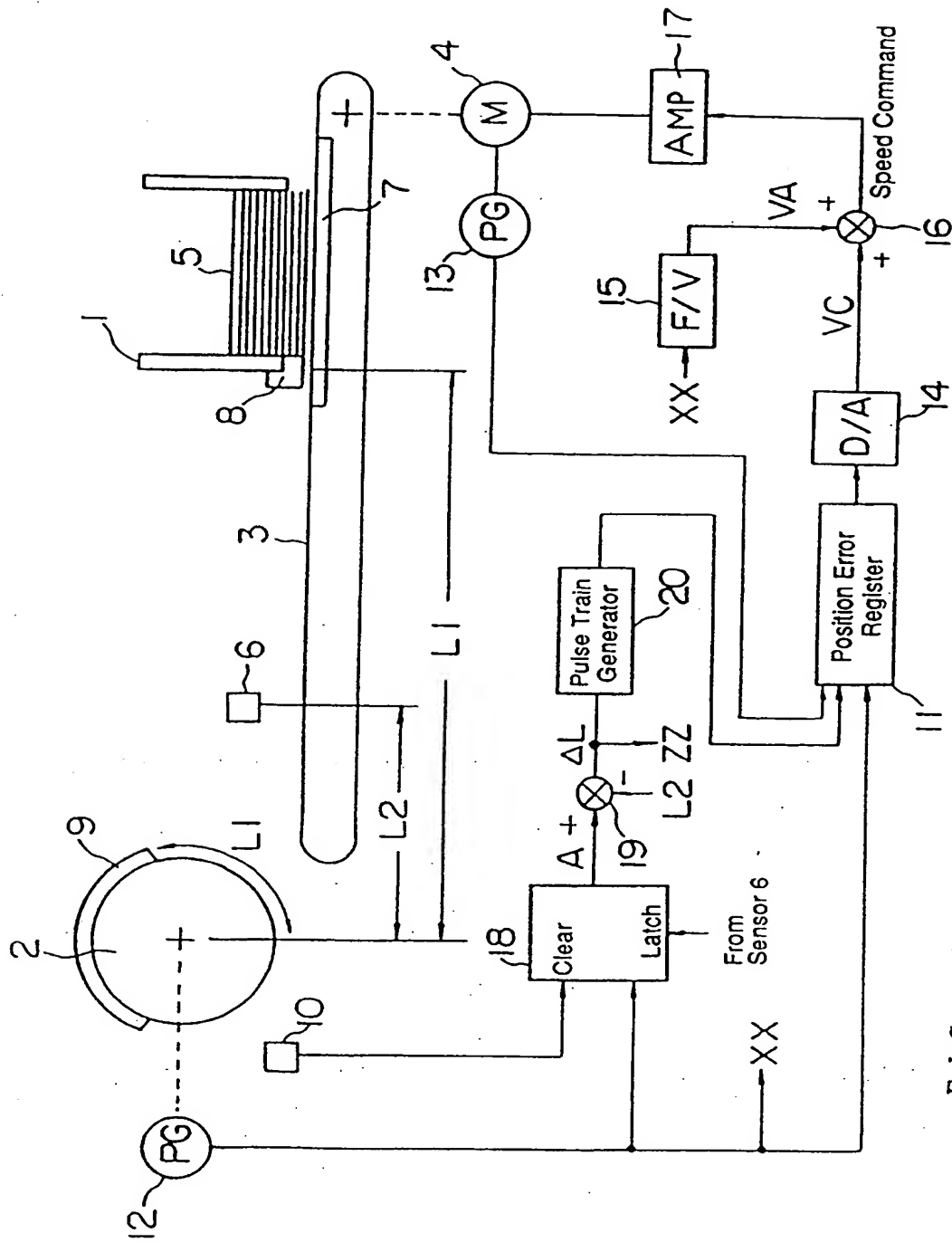


FIG. 1

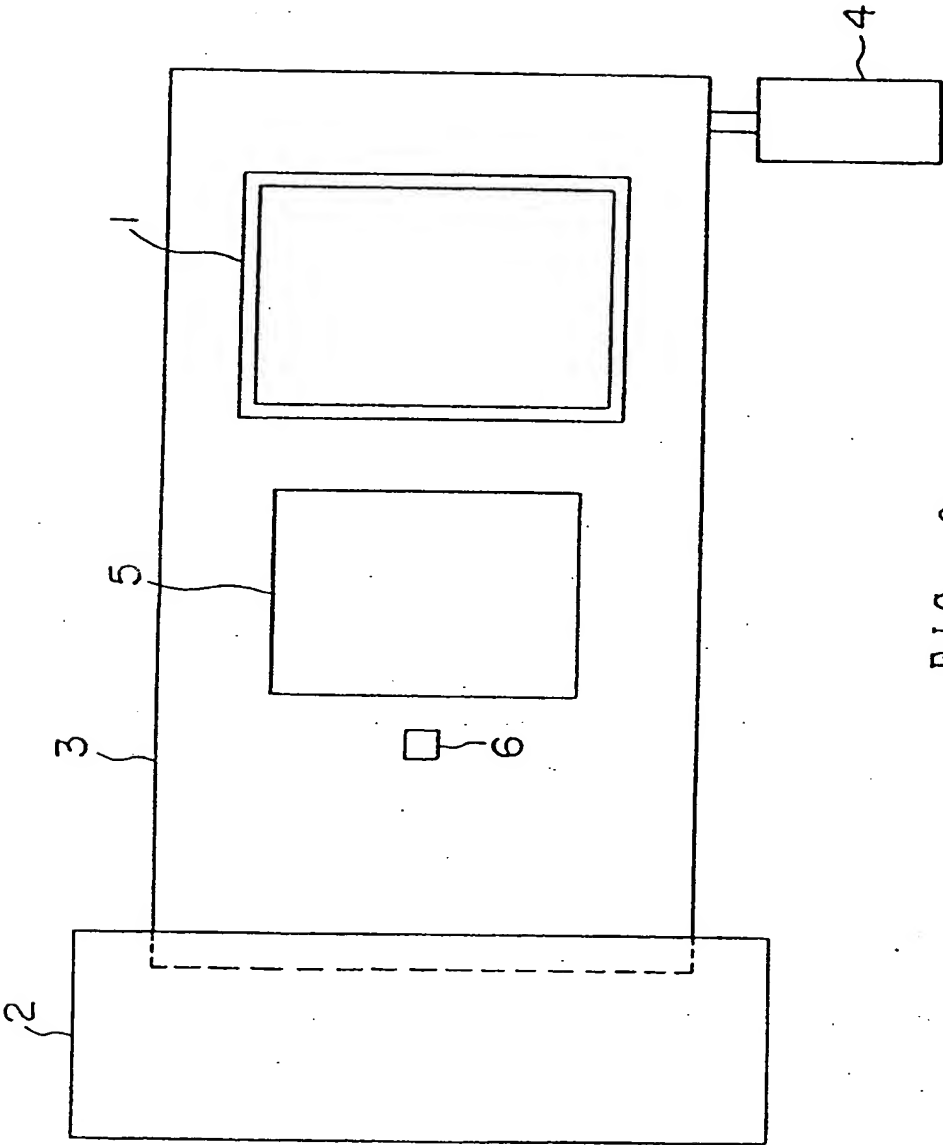


FIG. 2

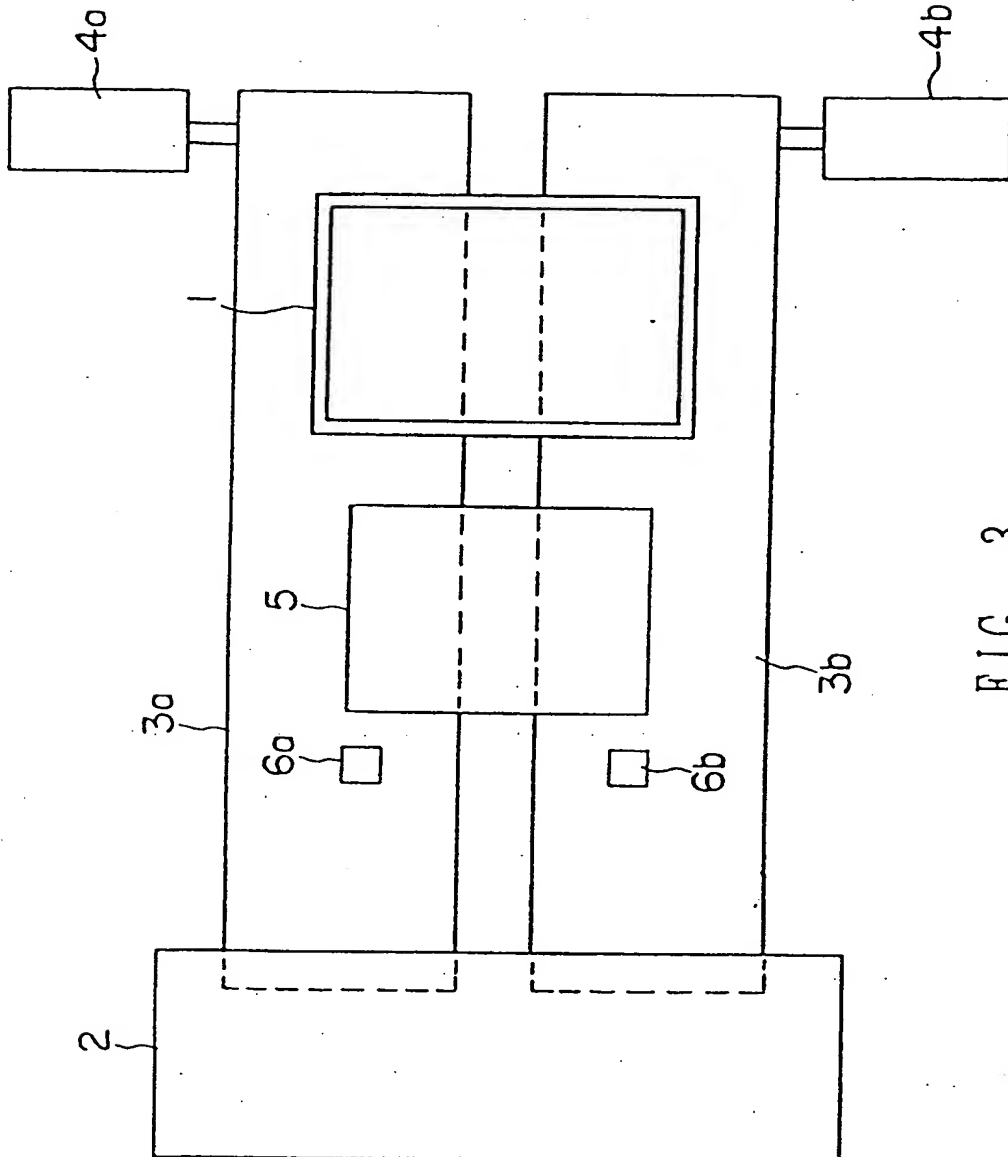


FIG. 3

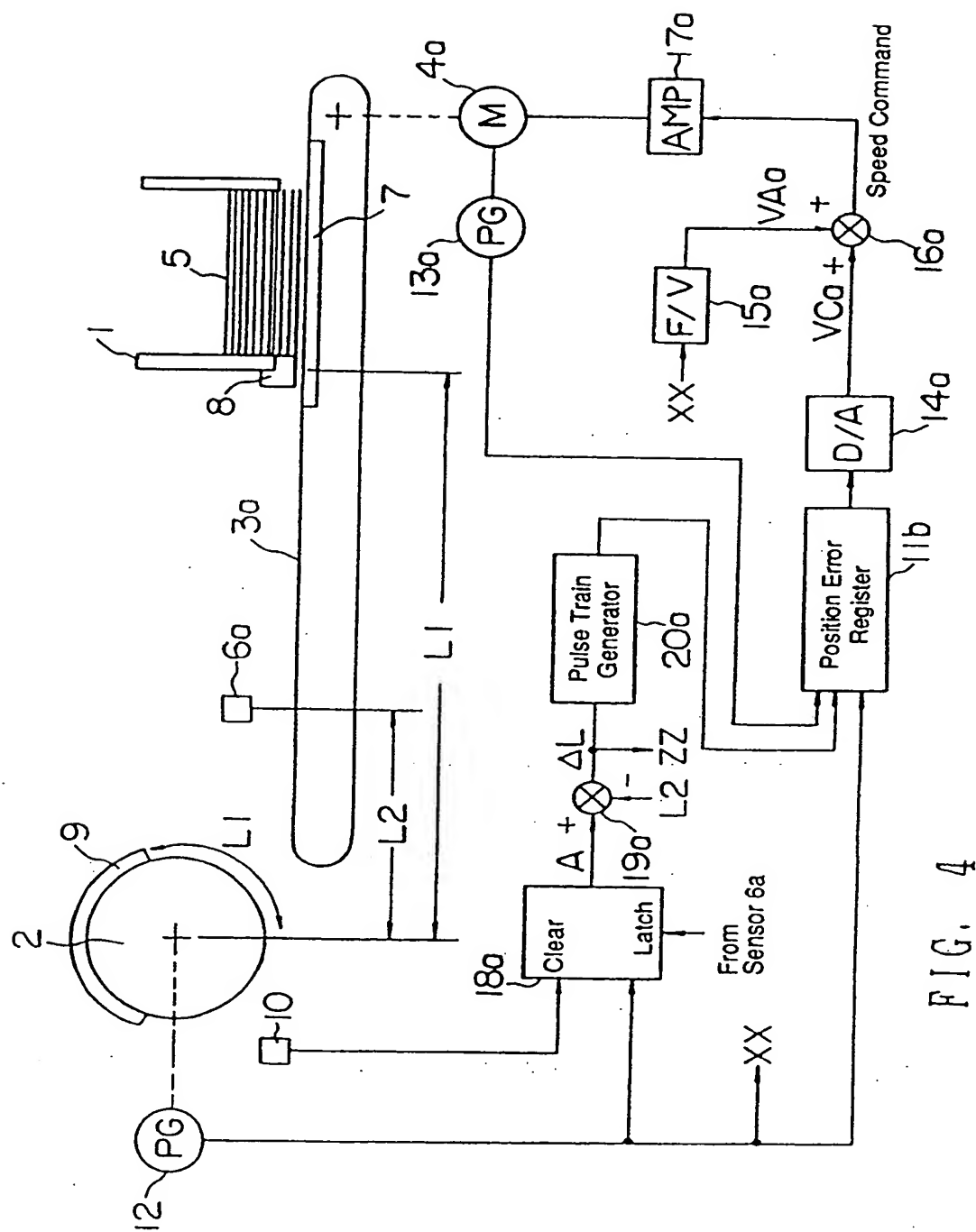


FIG. 4

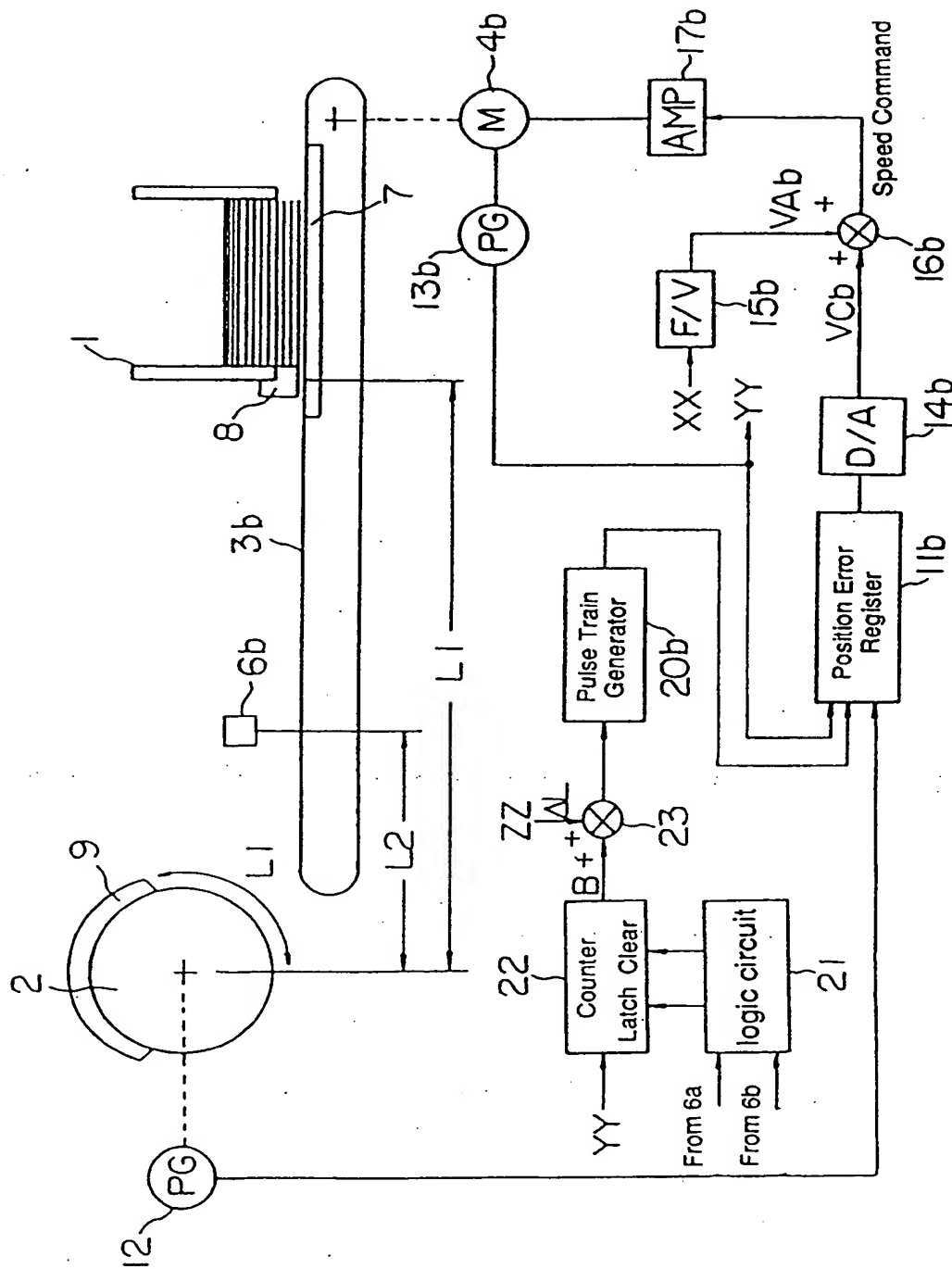


FIG. 5

INTERNATIONAL SEARCH REPORT

International Application No PCT/JP91/00480

I. CLASSIFICATION OF SUBJECT MATTER (if several classification symbols apply, indicate all) *		
According to International Patent Classification (IPC) or to both National Classification and IPC		
Int.-Cl ⁵ B65H5/22, B65H5/34, B65H3/12, B65H9/00, B65H43/00, B41F21/00		
II. FIELDS SEARCHED		
Minimum Documentation Searched ?		
Classification System	Classification Symbols	
IPC	B65H3/12, 5/22, 5/34, 9/00, 43/00, B41F5/24, 21/00, 21/12	
Documentation Searched other than Minimum Documentation to the Extent that such Documents are Included in the Fields Searched *		
Jitsuyo Shinan Koho	1926 - 1990	
Kokai Jitsuyo Shinan Koho	1971 - 1990	
III. DOCUMENTS CONSIDERED TO BE RELEVANT *		
Category *	Citation of Document, ¹¹ with indication, where appropriate, of the relevant passages ¹²	Relevant to Claim No. ¹³
A	JP, B2, 55-42022 (Shoji Matsuo), October 28, 1980 (28. 10. 80), (Family: none)	1-4
A	JP, U, 64-47721 (Tokyo Hoso Kikai K.K.), March 24, 1989 (24. 03. 89), (Family: none)	1-4
A	JP, A, 58-69639 (M.A.N. Roland Druckmaschinen AG), April 25, 1983 (25. 04. 83), & US, A, 4,458,893	1-4
A	JP, A, 63-91251 (Kyokuto International Corp.), April 21, 1988 (21. 04. 88), (Family: none)	1-4
A	JP, U, 55-172243 (Hitachi, Ltd.), December 10, 1980 (10. 12. 80), (Family: none)	3
<p>* Special categories of cited documents: ¹⁰</p> <p>"A" document defining the general state of the art which is not considered to be of particular relevance</p> <p>"E" earlier document but published on or after the international filing date</p> <p>"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)</p> <p>"O" document referring to an oral disclosure, use, exhibition or other means</p> <p>"P" document published prior to the international filing date but later than the priority date claimed</p> <p>"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</p> <p>"X" document of particular relevance: the claimed invention cannot be considered novel or cannot be considered to involve an inventive step</p> <p>"Y" document of particular relevance: the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art</p> <p>"d" document member of the same patent family</p>		
IV. CERTIFICATION		
Date of the Actual Completion of the International Search	Date of Mailing of this International Search Report	
June 13, 1991 (13. 06. 91)	July 1, 1991 (01. 07. 91)	
International Searching Authority	Signature of Authorized Officer	
Japanese Patent Office		

Form PCT/ISA/210 (second sheet) (January 1985)